



Reg. No. :

Name :

**Eighth Semester B.Tech. Degree Examination, November 2013
(2008 Scheme)**

08.804 : COMPUTER INTEGRATED MANUFACTURING (MU)

Time : 3 Hours

Max. Marks : 100

- Instructions :** 1) Answer **all** questions of Part – A.
2) Answer **one** question from **each** Module of Part – B.

PART – A

1. Explain integration in manufacturing technology.
2. Differentiate between DBMS and RDBMS.
3. Bring out the benefits of CAPP System.
4. How can we avoid stick-slip and back lash in machine tools ?
5. Describe the significance of MAP in CIM environment.
6. Explain briefly about the APT language.
7. Enumerate the factors to be considered in selecting a suitable material handling method for a particular manufacturing operation.
8. Describe the role of management in CIM.
9. What are basic robot motions ? Explain briefly.
10. Give the basic structure of an expert system. **(10×4=40 Marks)**



PART – B

Module – I

11. a) In what ways have computers had an impact on manufacturing ? **10**
- b) Explain the CAD/CAM system activities. **10**

OR



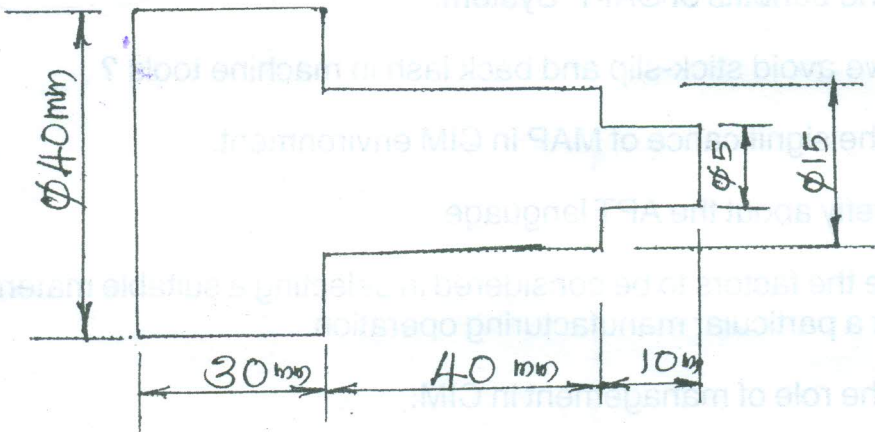
12. a) Give a specific example in which the variant system of CAPP is desirable, and one in which generative system is desirable. Explain. 10
- b) Explain the role of computers in MRP. 10

Module – II

13. a) List the steps involved to produce an NC program. Briefly explain sequence number, preparatory function, miscellaneous function and canned cycle. 10
- b) Describe the open loop and closed loop controls with examples. 10

OR

14. a) Explain with block diagrams the application of an adaptive control suitable for a turning operation. 10
- b) Prepare a CNC program to machine the component shown in figure. Billet size $\phi 40 \times 80 \text{ mm}$. 10



Module – III

15. a) Explain in detail the communication networks in manufacturing. 10
- b) How are robots programmed to follow a certain path? 10

OR

16. a) What factors have led to the development to automated guided vehicles? Do they have any disadvantages? Explain in detail. 10
- b) Explain the operation of a machine vision system. 10